Selective linear or quadratic coupling in an optomechanical system

André Xuereb1,2,* and Mauro Paternostro1

1Centre for Theoretical Atomic, Molecular, and Optical Physics, School of Mathematics and Physics, Queen’s University Belfast, Belfast BT7 1NN, United Kingdom
2Department of Physics, University of Malta, Msida MSD 2080, Malta

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There has been much interest recently in the analysis of optomechanical systems incorporating dielectric nanor or microspheres inside a cavity field. We analyze here the situation when one of the mirrors of the cavity itself is also allowed to move. We reveal that the interplay between the two oscillators yields a cross-coupling that results in, e.g., appreciable cooling and squeezing of the motion of the sphere, despite its nominal quadratic coupling. We also discuss a simple modification that would allow this cross-coupling to be removed at will, thereby yielding a purely quadratic coupling for the sphere.

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Several early optomechanical systems [1–3] were straightforward realizations of ideas first proposed by Braginsky and Manukin [4,5], and took the form of a Fabry–Pérot cavity with one moving mirror. These systems are naturally modeled by the Hamiltonian [6,7] (we will use units such that ħ = 1 throughout this paper) $\hat{H} = \hat{p}^2/2m + m\omega^2_\text{g}x^2/2 + H_{\text{lin}}$, where we have introduced the term

$$\hat{H}_{\text{lin}} = (\omega_\text{c} - g_1\hat{x})\hat{a}^\dagger \hat{a} \quad (1)$$

with $\hat{a}$ the annihilation operator representing the cavity field (frequency $\omega_\text{c}$), $\hat{x}$ [$\hat{p}$] the position [momentum] operator for the moving mirror (frequency $\omega_m$ and mass $m$), and $g_1$ the optomechanical coupling constant. Physically, $\hat{H}_{\text{lin}}$ admits a remarkably simple interpretation: The instantaneous position of the mirror changes the length of the cavity, and thus its resonance frequency.

The light–mirror interaction inherent in Eq. (1) enables the passive cooling of the mechanical system, an effect that has been demonstrated in a vast array of experimental settings [1,2,8–10] and that has been progressively pushed to the point that optical cooling to the mechanical quantum ground state was recently achieved [11]. Moreover, it has long been recognized that the mechanical and optical fields can be prepared in an entangled steady state [12,13] by the means of Eq. (1). Bhattacharya and Meystre [14] proposed a different paradigm, where the moving mirror was translucid and placed inside the cavity, a configuration that was implemented in the seminal experiment reported in Refs. [15,16]. A remarkable feature of this model is that, under the right conditions and differently from the above, the light–mirror interaction may be described through an optomechanical Hamiltonian quadratic in the position operator of the mechanical system and reading

$$\hat{H}_{\text{quad}} = (\omega_\text{c} + g_2\hat{x}^2)\hat{a}^\dagger \hat{a}, \quad (2)$$

where $g_2$ is a coupling constant. This model has several interesting properties, including the possibility of performing QND measurements of the occupation number of the oscillator [17], but precludes cooling to leading order in the linearized regime achieved when the cavity field is populated by a very large number of photons [18] (see, however, Ref. [19] for a treatment that goes beyond the linearized dynamics of the system).

In this paper we propose to combine these two scenarios. Our system is reminiscent of several “hybrid” optomechanical proposals [20–26] and realizations [27], which examine the interaction between the motion of mechanical oscillators and that of atomic systems. Let us consider the system shown in Fig. 1, which includes a small dielectric scatterer (herein referred to as the sphere) held in a harmonic potential inside a cavity [28–34], one of whose end mirrors is allowed to oscillate. As we shall show, this system allows us to exert a degree of control on the state of the motion of the sphere through its indirect interaction with the end mirror, mediated by the cavity field. As a result of this, and by means of a judicious choice of operating parameters, we will show that passive cooling of the motion of the sphere, despite its apparent quadratic coupling to the cavity field, and squeezing of this same motion are both possible. Moreover, we expect that the interaction between the cavity field, sphere, and end mirror gives rise to steady states with interesting genuinely tripartite entangled [35] or nonlocal [36] properties.

One might think that the Hamiltonian that describes this compound system would simply be given by the sum of the interaction terms in $\hat{H}_{\text{lin}}$ through the position $\hat{x}_1$ of the end mirror and $\hat{H}_{\text{quad}}$ through the position $\hat{x}_2$ of the sphere. As natural as this might seem, this would not be entirely correct, given that the position of the end mirror not only defines the resonance frequency of the cavity field (as captured through the interaction in $\hat{H}_{\text{lin}}$) but also determines the relative position of the cavity field (anti)nodes and the sphere. This means that for the configuration shown in Fig. 1, i.e., for a cavity pumped from the leftmost (fixed) mirror, the light field couples quadratically to the relative position operator $\hat{x}_1 - \hat{x}_2$. We can thus write the Hamiltonian

$$\hat{H}_{\text{lp}} = [\omega_\text{c} - g_1\hat{x}_1 + g_2(\hat{x}_1 - \hat{x}_2)^2]\hat{a}^\dagger \hat{a}, \quad (3)$$

where the subscript “lp” reminds us that the system is pumped from the left. In Appendix A, we examine the other possibilities for the geometry of the pump field.

The remainder of this paper is structured as follows. Section I will set the stage for exploring the dynamics of our system, deriving in particular the Hamiltonian and the linearized equations of motion. Section II subsequently
makes use of numerical simulations to discuss the resulting dynamics. As an application of our scheme, we show that the cross-coupling between the two oscillators, cf. Eq. (3), gives rise to efficient cooling of the mechanical motion of the sphere. In Sec. III we discuss squeezing of the motion of the sphere and demonstrate that this motion can be squeezed appreciably if the coupling constant $g_2$ is large enough. Finally, we conclude with an outlook of possible future directions.

I. DYNAMICS IN THE LINEARIZED REGIME

Let us start by considering the model in Fig. 1. Classically, the intensity of the field within the cavity at a distance $z$ from the right mirror is given by $I(z) = I_0 \sin^2(kz)$, where $I_0$ depends on the value of the wave number $k$ and the amplitude of the input field. To treat our oscillators quantum mechanically we perform the replacement

$$z \rightarrow \hat{x}_1 - \hat{x}_2 + d, \quad (4)$$

where $d$ is the distance between the equilibrium positions of the two oscillators. Let us choose $d$ such that $kd = n\lambda / 2 (n \in \mathbb{Z})$, with $\lambda = 2\pi / k$ the wavelength of the input light. With this choice, the sphere oscillates about a node or an antinode of the cavity field. The interaction Hamiltonian involving the sphere thus takes the form

$$\hat{H} \propto \sin^2[k(\hat{x}_1 - \hat{x}_2)]\hat{a}^\dagger \hat{a}. \quad (5)$$

We now expand Eq. (5) as a series, stopping at the lowest order, introduce dimensionless mechanical operators [obtained by dividing out the extent of the zero-point fluctuations $\Delta_{0,j} = \sqrt{\hbar / (m_j \omega_j)}$] of each oscillator, where $m_j$ is the mass and $\omega_j$ the oscillation frequency of the mirror ($j = 1$) or the sphere ($j = 2$), and add back the linear optomechanical coupling between $\hat{a}$ and $\hat{x}_1$. This gives us the total interaction Hamiltonian

$$\hat{H}_\text{int} = [-g_1 \hat{x}_1 + g_2 (\chi \hat{x}_1 - \hat{x}_2)^2]\hat{a}^\dagger \hat{a}, \quad (6)$$

where, as before, $g_1$ and $g_2$ are optomechanical coupling constants and $\chi = \omega_{0,1} / \omega_{0,2}$. The signs in front of the coupling constants are chosen to aid interpretation: The system shown in Fig. 1 has positive $g_1$, and $g_2 > 0$ implies that the sphere oscillates about an antinode, i.e., a point of stable equilibrium. A full description of the system requires also the free Hamiltonian, which we write in a frame rotating at the frequency of the driving laser $\omega_L$,

$$\hat{H}_\text{free} = -\Delta \hat{a}^\dagger \hat{a} + \frac{1}{2} \sum_{j=1}^{\infty} \omega_j \left( \hat{x}_j^2 + \hat{p}_j^2 \right), \quad (7)$$

as well as cavity-pump ($\hat{H}_\text{pump}$) and dissipation Hamiltonians ($\hat{H}_\text{diss}$), which will be left unspecified. Here, $\Delta = \omega_L - \omega_c$ is the cavity–pump detuning. The full Hamiltonian is thus $\hat{H} = \hat{H}_\text{int} + \hat{H}_\text{free} + \hat{H}_\text{diss} + \hat{H}_\text{pump}$. The corresponding equation of motion for the cavity field operator is

$$\dot{\hat{a}} = (i \Delta - \kappa_c) \hat{a} + i [g_1 \hat{x}_1 + g_2 (\chi \hat{x}_1 - \hat{x}_2)^2] \hat{a} - \sqrt{2\kappa_c} \hat{a}_\text{in}, \quad (8)$$

where $\kappa_c$ is the cavity amplitude decay rate, and $\hat{a}_\text{in}$ is the input field. As for the sphere and mechanical mode, the dynamics is encompassed by

$$\dot{\hat{x}}_j = \omega_j \hat{p}_j, \quad \dot{\hat{p}}_j = -\kappa_1 \hat{x}_1 + (g_1 - \chi \hat{x}_1) \hat{a} \hat{a}^\dagger \hat{a} - 2\gamma_1 \hat{p}_j - \sqrt{2\gamma_1} \hat{x}_1, \quad (9)$$

$$\dot{\hat{p}}_2 = -\kappa_2 \hat{x}_2 + \hat{X} \hat{a} \hat{a}^\dagger \hat{a} - 2\gamma_2 \hat{p}_2 - \sqrt{2\gamma_2} \hat{x}_2, \quad (10)$$

where $\hat{X} = 2g_2 (\chi \hat{x}_1 - \hat{x}_2), \gamma_j$ are the mechanical decay rates, and $\hat{\xi}_j$ is the self-adjoint zero-mean operator describing the Brownian noise affecting oscillator $j = 1, 2$, and characterized by the correlation functions $[37]$

$$\langle \hat{\xi}_j(t) \hat{\xi}_j(t') \rangle = (2n_j + 1) \delta_{jj} \delta(t - t'), \quad (11)$$

where $n_j = [e^{\hbar \omega_j / k_b T_j} - 1]^{-1}$ is the equilibrium phononic population of oscillator $j$ at temperature $T_j$ ($k_B$ is the Boltzmann constant).

A. Classical steady-state solution

Equations (9) are tackled in two steps. First we replace each operator $\hat{\xi}$ by its quantum-mechanical mean value $\bar{\xi}$. The resulting equations of motion are identical to the classical ones. Their solution is then used in a second step, as described in Sec. IB, to analyze the linear evolution of the system. We remark here that $\bar{\xi}_j = 0$ ($j = 1, 2$), and that $\bar{a}_\text{in}$ relates to the input power as $P_\text{in} = \hbar \omega_c |\bar{a}_\text{in}|^2$. When the dynamics is stable, the long-time classical solutions are

$$\bar{\xi}_2 = \frac{1}{2} g_2 |\bar{a}|^2 \frac{\Omega_1}{\Omega_2}, \quad \bar{x}_2 = \bar{x}_1 + \frac{1}{2} g_2 |\bar{a}|^2 \frac{\Omega_1}{\Omega_2}, \quad (12)$$

where we have replaced the detuning $\Delta$ with $\Delta = \Delta + g_1 \bar{x}_1 - g_2 (\chi \bar{x}_1 - \bar{x}_2)^2$ and introduced the quantities

$$\Omega_1 = \omega_1 + 2g_2 \chi^2 |\bar{a}|^2 \frac{\Omega_1}{\omega_2 + 2g_2 |\bar{a}|^2}, \quad \Omega_2 = \omega_2 + 2g_2 |\bar{a}|^2. \quad (13)$$

Equations (11) diverge in a notable way from the analogous ones reported in Ref. [18]. The latter case corresponds to ours upon going to the infinite-mass limit for the end mirror ($\chi = g_1 = 0$). From Eqs. (11) it then follows that $\bar{x}_2 = \bar{x}_1 = 0$. An immediate consequence of this is that in the linearized equations of motion, as obtained in the next section, the motion of the mirror is decoupled from the rest of the system [cf. Eq. (B1)]. Under these conditions, therefore, the effective mechanical decay rate of the sphere cannot be altered by the
dynamics in the linear approximation; i.e., the motion of the sphere cannot be cooled by a quadratic interaction with the cavity field. Outside the infinite-mass limit, however, the two oscillators interact to avoid this pitfall. As we shall see later on, one can choose the parameters such that cooling of the sphere to a temperature determined mostly by the properties of the end mirror is indeed possible, thus demonstrating the control mechanism at the center of our work.

**B. Linearized equations of motion**

Having at hand the explicit form of the operators’ mean values, we now consider the zero-mean quantum fluctuations $\delta a = \bar{a} - a$. One can truncate the equations of motion to first order in the fluctuations, yielding the set of linear equations of motion

$$\frac{d}{dt}\delta R = A \delta R + \delta R_m. \quad (13)$$

Here, we have defined the vectors of quadrature fluctuations $\delta R = (\delta \xi, \delta \bar{\rho}, \delta \bar{p}_1, \delta \bar{p}_2)^T$, where $\delta \xi = (\delta \bar{a} + \delta \bar{a}^\dagger)/\sqrt{2}$ and $\delta \bar{p} = i(\delta \bar{a}^\dagger - \delta \bar{a})/\sqrt{2}$, as well as $\delta R_m = -(\sqrt{2} \kappa \delta x_m, \sqrt{2} \kappa \delta \bar{p}_m, 0, 0, \sqrt{2} \gamma_1, 0, 0, \sqrt{2} \gamma_2)^T$ with $\delta x_m$ and $\delta \bar{p}_m$ that are defined analogously to $\delta \xi$ and $\delta \bar{p}$. The input noise field obeys $\langle \delta a_n(t) \delta a_n(t') \rangle = \langle \delta a_m(t) \delta a_m(t') \rangle = 0$ and $\langle \delta a_n(t) \delta a_m(t') \rangle = \delta(t - t')$. Moreover, we have introduced the drift matrix $A$, whose (lengthy) expression is given in Appendix B. Stability of the dynamics encompassed by Eq. (13) is easily studied by using the well-known Routh-Hurwitz criterion ([38], Sec. 2.3.2), which (in its most straightforward formulation) guarantees the existence of a stable solution if all of the eigenvalues of $A$ have negative real part. All of the following analysis is conducted in this stable regime.

The linearized dynamics for the operator increments can be derived from a quadratic effective Hamiltonian. For a fixed set of parameters, the dynamics therefore leads any initial Gaussian state to a unique final Gaussian steady state. This steady state has zero first moment, since we operate in a shifted picture involving only zero-mean operator increments, and the matrix of second moments $V = [(R(t) \otimes R(t')) + (R(t) \otimes R(t'))^T]/2$ satisfies the Lyapunov equation $AV + VA^T = -D$, where

$$D\delta(t - t') = \frac{1}{2}[(R_m(t) \otimes R_m(t')) + (R_m(t) \otimes R_m(t'))^T].$$

We remark that the Lyapunov equation admits a compact solution in in terms of the eigensystem of $A$ ([38], Sec. 5.0.4). Having at hand the covariance matrix $V$, we can readily analyze the (Gaussian) steady state of the system, including bipartite entanglement between any two components of the system, genuine tripartite entanglement, or occupation numbers for the harmonic oscillators.

**II. COOLING OF THE SPHERE**

In this section, we shall demonstrate the claimed cooling mechanism for the trapped sphere, and the control we can operate on it through the means of the mechanical mirror. Before specifying the values of the various parameters that enter our dynamical equations, let us give explicit formulas for $g_1$ and $g_2$. The basic theory of cavity optomechanics identifies $g_1$ with the first-order change in the cavity resonance frequency when the end mirror moves by a distance $x_{0_1}$ [39]. For a cavity of length $L$ we can thus write [40]

$$g_1 = \frac{\omega_c}{L} x_{0_1} = \frac{\omega_c}{L} \sqrt{\frac{h}{m(\omega)}}. \quad (14)$$

For $g_2$, in the case of spheres that are not too large, we use the expression in Ref. [32]

$$g_2 = \pm \frac{3V}{4V_c} \text{Re} \left\{ e_1 + 1 \right\} \sqrt{\frac{\pi}{2}} \sqrt{\frac{c}{k^3}}, \quad (15)$$

where $V$ is the volume of the sphere, $V_c = \frac{4}{3} \pi w^2 L$ is the mode volume for a cavity with waist $w$, $k = 2\pi/\lambda$ is the wave number of the driving field, and $\lambda$ is its wavelength. The sign of this expression is chosen depending on whether the sphere is at a node (−) or an antinode (+) of the cavity field. In the case of a lossless dielectric of real refractive index $n$, $\text{Re}(e_1) = n^2$, and we can write this expression as

$$g_2 = \pm \frac{12\pi n^2 - 1}{2} \frac{\omega_c}{2L} \frac{h}{\rho(\lambda n)^2 \omega_2}, \quad (16)$$

where $\rho$ is the mass density of the material composing the sphere. Note, in particular, that $g_2$ is independent of the radius $r$ of the sphere. For silica $\rho = 2650 \text{ kg m}^{-3}$ and, in the near infrared, $n \approx 1.5$. We shall use $\lambda = 1064 \text{ nm}$, $L = 0.5 \text{ cm}$, $\kappa_c = 2\pi \times 50 \text{ kHz}$, $r = 0.5 \mu \text{m}$, $w = 40 \mu \text{m}$ (which can all be found in Ref. [34]), and $m_1 = 40 \text{ ng}$ [41]. For the mechanical damping constants, we take the values $\gamma_1 = 2\pi \times 140 \text{ Hz}$ and $\gamma_2 = 2\pi \times 0.5 \mu \text{Hz}$. At the two nominal frequencies $\omega_1 = 1 \text{ MHz}$ and $\omega_2 = 2\pi \times 200 \text{ kHz}$, we find $g_1 \approx 2\pi \times 36 \text{ Hz}$, $g_2 \approx -2\pi \times 10 \mu \text{Hz}$ at a node of the cavity field, and $\chi \approx 2.9 \times 10^{-2}$. In what follows we will not constrain ourselves to these particular values of $\omega_j$, however, and will scale $g_j$ and $\chi$ appropriately. In passing, we note that $g_1$ and $g_2$ can be made larger by decreasing the length of the cavity or lowering the mechanical oscillation frequencies. Moreover, $g_1$ can be increased by lowering the effective mass of the moving mirror, while $g_2$ by using a sphere with a larger refractive index or a cavity with a smaller waist. Finally, the value of $\chi$ can be made larger by increasing the ratios $\omega_2/\omega_1$ and $m_2/m_1$.

We have already mentioned how $\chi = 0$ gives rise to the steady-state solution $\bar{x}_0 = 0$ [18]. In the linearized regime, the motion of the sphere is thus decoupled from that of the dynamics of the cavity-mirror system. This can easily be seen by substituting $\chi = 0$ and $\xi_2 = 0$ into the drift matrix $A$. A straightforward method to explore the implications of the coupling induced by our interaction Hamiltonian is thus to look at cooling of the motion of the sphere. A sample of such data is shown in Fig. 2. The cases (i) $\omega_2 \gtrsim \omega_1$ or (ii) $\omega_2 \lesssim \kappa_c$ have been excluded from the plot for reasons that will be clarified later on. We see that, for each $\omega_1$, there exists a band of frequencies $\omega_2$ for which the steady-state occupation for the spherical motion is significantly below the starting value. Moreover, for a particular $\alpha_{opt} = \omega_1/\omega_2$ that depends most strongly on the properties of the mirror (in particular, the constant parameter $g_1 \sqrt{\omega_1}$), the motion of the mirror and sphere equilibrate to the same occupation number. The data displayed in Fig. 2 show the reduction of the occupation number of the sphere by almost three orders of magnitude. However, in our numerical
respectively. The rest of the parameters used for generating this plot are in contact with separate baths at temperatures of 50 mK and 1 K, respectively. The rest of the parameters used for generating this plot are in Sec. II. Inset: Cut of the main figure along the line \( \omega_1 = 10 \kappa_c \) (blue, lower curve). The red, upper curve shows the occupation number in the absence of any cooling. The dashed line indicates the value of \( \omega_2 \) for which the lowest occupation number is reached.

exploration we have seen evidence that this is not an upper limit to the efficiency of the process. Indeed, decreasing the temperature of the thermal bath to which the mirror is coupled will yield a correspondingly lower occupation number for the sphere, as a result of dynamical equilibration of the sphere through the mechanical mirror.

The basic mechanism through which this cooling process occurs is a hybridization of the motion of the two oscillators. For moderately large values of \( \omega_1/\omega_2 \), increasing the input power from zero causes the frequencies of the normal modes of the system, given by the imaginary parts of the eigenvalues of \( A \), to shift. Thus, for instance, the mode that at \( P_n = 0 \) describes the mirror motion shifts to a smaller frequency \( \tilde{\omega}_1 \) [42]. At the point where \( \tilde{\omega}_1 \approx \omega_2 \), the two modes hybridize and cooling ensues. For \( \omega_1/\omega_2 < 1 \), this hybridization is no longer possible. However, if \( \omega_1/\omega_2 \) is too large, the system reaches instability before the criterion \( \tilde{\omega}_1 \approx \omega_2 \) can be satisfied. Conversely, if \( \omega_1/\omega_2 \) is not large enough, the power at which \( \tilde{\omega}_1 \approx \omega_2 \) is satisfied is too low for efficient cooling. Such hybridization can be seen in Fig. 3, where we plot the case \( \omega_1 = 10 \kappa_c \), at the optimal values for \( \omega_2 \) and \( \tilde{\Delta} \).

Another unique feature of our system is that, after cooling the sphere, we can switch to coupling light into the cavity from the moving mirror. As explained in Appendix A, this means that the Hamiltonian that couples the motion of the sphere to the optical field is purely quadratic. This renders possible, for example, quantum nondemolition (QND) measurements of the energy of the harmonic oscillator embodied by the sphere. This protocol requires that the cavity can be pumped from either end mirror, but is deterministic and otherwise less demanding than, e.g., measurement-based schemes for achieving the same [43].

III. SQUEEZING OF MECHANICAL MOTION

The coupling of mechanical elements to a light field, both linearly [44] and quadratically [19], can give rise to squeezing of the mechanical motion, where the quantum nature of the optomechanical interaction acts to suppress the noise in one of the quadratures of the mechanical motion. To investigate the occurrence of mechanical squeezing in our setup we set the temperature of the baths coupled to both oscillators to zero. For the parameters given above, there is no observable squeezing.
We conclude this section by noting that the larger quadratic
 coupling strengths necessary for generating and observing
 squeezing can be obtained by making use of avoided crossings
 between pairs of cavity modes [16].

IV. CONCLUSIONS

We have explored a system consisting of an optomechanical
cavity with an additional intracavity particle whose motion is
coupled quadratically to the cavity field. A direct coupling
between the two moving elements arises naturally in this
system. This coupling can be turned off and on at will by
choosing which port the cavity is driven from, and therefore
provides complete control over whether the interaction with
the particle is purely quadratic, or whether it has some linear
character. As examples of the potential of our scheme, we
have discussed the possibility of cooling the motion of the
sphere, despite its nominal quadratic coupling, as well as
squeezing of this same motion. Our work opens up interesting
perspectives for quantum state transfer between two oscillators
and the distribution of multipartite entanglement. Moreover,
the system that we have addressed leaves room for asking
interesting questions on the nonlocal nature of the three-mode
state achieved via the coupling mechanisms addressed here,
a goal that can be pursued, for instance, through the formal
apparatus recently put forward in Ref. [36].

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APPENDIX A: ALTERNATIVE PUMPING GEOMETRIES

The function of this Appendix is to elucidate the differences
between pumping the cavity from the immobile mirror, from
the moving mirror, or from both ends. These three possibilities,
which are exhaustive in one-dimensional geometries, are
illustrated in Fig. 5. The geometry used throughout this paper
is shown in Fig. 5(b). The most “natural” case, where the cavity
field is symmetric with respect to coordinate inversion, is
illustrated in Fig.5. The geometry used throughout this paper
is shown in Fig. 5(b). The most “natural” case, where the cavity
field is symmetric with respect to coordinate inversion, is
depicted in Fig. 5(a). In both these situations, when the mirror
on the right moves, the nodal structure shifts with respect to
the laboratory frame, yielding a term in the Hamiltonian that
couples the two oscillators. In the case of Fig. 5(c), however,
the nodes of the field do not shift when the mirror moves, such
that there is no longer any cross-coupling between the two
oscillators. A mathematical explanation for why this must be
so follows later on in this Appendix; the next paragraph aims
to provide a physical basis for understanding this effect.

Consider a classical picture and single-sided driving. The
mirror being driven is interacting with four running waves
(the incident and reflected field outside the cavity, and the two
making up the cavity standing field), whereas the other mirror

\[ S_j = \frac{1}{2 \min\{\langle \hat{x}_j^2 \rangle, \langle \hat{p}_j^2 \rangle\}} \]  

as plotted in Fig. 4(b) for \( j = 2 \). In other words, \( S_j > 1 \) only
when the variance of one of the quadratures dips below the \( \frac{1}{2} \)-
quantum level that is due to vacuum fluctuations in the ground
state. We find a maximal \( S_2 \approx 1.2 = 0.7 \text{ dB} \) (\( \langle \hat{p}_2^2 \rangle \approx 0.43 \))
just before the instability threshold, which compares favorably
to the amount of squeezing obtained in Ref. [19] for pure
quadratic coupling.
is interacting with three (the two inside the cavity and the transmitted wave); i.e., there is no incident wave impinging on the undriven mirror from the outside. This breaks the coordinate-inversion symmetry of the situation and renders moot all arguments relying on such symmetry. A resonant cavity pumped from one end is a special case, since it transmits all incident light. Therefore, there is no reflected field at the driven mirror in this case, and both mirrors interact with three running waves. This restores the inversion symmetry, and interference must result in a symmetric (antisymmetric) field distribution. This yields an antinode (a node) at the center of the cavity, as expected.

Outside the resonant case, the situation is not as intuitive. Interference and the boundary conditions ensure that the distance of the nodes from the undriven mirror is fixed. To see why this can be so, consider the following. At perfect reflectors the field must vanish; such a cavity has zero linewidth and only admits fields on resonance. At imperfect reflectors, which have a nonzero transmissivity, the field does not vanish; this gives rise to a nonzero linewidth and also explains why it is possible for the cavity nodes to have different distances from the two mirrors. In particular, it does not hold that nodes must be located at the two mirrors.

A symmetric situation is recovered when the cavity is driven from both mirrors with a fixed and properly chosen phase between the two driving fields. Interference is once again responsible for a cavity field that is symmetric. In this case, we arrive at the conclusion that the cavity field has a node or an antinode at the center.

This interesting result can easily be seen for cases (b) and (c), and analogously for case (a), by calculating the field inside the cavity explicitly. The methodology used here is entirely equivalent to the very well established transfer-matrix formalism, which is itself a compact way of solving the Helmholtz equation of one-dimensional electromagnetism in the presence of arbitrary reflectors, and therefore respects boundary conditions fully. The resulting field at a distance $z$ from the right mirror, normalized to the input field, is

$$E(z) = t [e^{ik(L-z)} + re^{ik(L+z)} + r^2 e^{ik(3L-z)} + \cdots]$$

where $L$ is the length of the cavity, $k$ the wave number of the field, $L(t)$ accounts for the spectral profile of the resonance, and $E(z)$ depends only on the distance from the right mirror. For simplicity, the two mirrors are assumed to be identical, with (real) reflectivity $r$ and transmissivity $t$, and any phase shifts upon reflection or transmission are absorbed in $L$; these simplifications are not crucial to deriving this result. In the good-cavity limit $r \to 1$, $E(z)$ reduces to the expected sinusoidal profile, with (anti)nodes lying at a fixed distance from the right (undriven) mirror.

In our notation, the part of the resulting interaction Hamiltonian that involves the sphere can therefore be represented as

$$\hat{H} \propto \begin{cases} \frac{1}{2} \hat{x}_1 - \hat{x}_2 \right| \hat{a}^\dagger \hat{a} & \text{(a)} \\ (\hat{x}_1 - \hat{x}_2) \hat{a}^\dagger \hat{a} & \text{(b)} \\ \hat{x}_2^2 \hat{a}^\dagger \hat{a} & \text{(c)} \end{cases}$$

with reference to the respective cases in Fig. 5. The main text can be adapted for the remaining cases by setting $\chi \to \chi/2$ [case (a)] or $\chi \to 0$ [case (c)].

**APPENDIX B: DRIFT MATRIX**

Here we provide the explicit form of the drift matrix $A$ for our problem. In order to aid comparison between data sets with different $g_1$ and $g_2$, we introduce the effective detuning $\Delta = \Delta + g_1 \bar{x}_1 - g_2 (\bar{x}_1 - \bar{x}_2)^2$. The resulting drift matrix reads

$$A = \begin{bmatrix} -\kappa_c & -\tilde{\Delta} & -[g_1 - 2g_2 \chi (\bar{x}_1 - \bar{x}_2)] \tilde{p} & 0 & -2g_2 \chi (\bar{x}_1 - \bar{x}_2) \tilde{p} & 0 \\ \bar{\Delta} & -\kappa_c & [g_1 - 2g_2 \chi (\bar{x}_1 - \bar{x}_2)] \bar{p} & 0 & 0 & 0 \\ 0 & 0 & 0 & -\omega_1 & 0 & 0 \\ [g_1 - 2g_2 \chi (\bar{x}_1 - \bar{x}_2)] \bar{k} & [g_1 - 2g_2 \chi (\bar{x}_1 - \bar{x}_2)] \tilde{k} & -\omega_1 - g_2 \chi (\tilde{x}_1^2 + \tilde{p}^2) & \cdots & -2\gamma_1 & g_2 \chi (\tilde{x}_1^2 + \tilde{p}^2) & 0 \\ 0 & 0 & 0 & 0 & 0 & \omega_2 \\ 2g_2 \chi (\bar{x}_1 - \bar{x}_2) \bar{k} & 2g_2 \chi (\bar{x}_1 - \bar{x}_2) \tilde{k} & g_2 \chi (\tilde{x}_1^2 + \tilde{p}^2) & 0 & -\omega_2 - g_2 \chi (\tilde{x}_1^2 + \tilde{p}^2) & -2\gamma_2 \end{bmatrix}$$

(B1)

The phase of the input field can be chosen, as is commonly done, to set $\tilde{p} = 0$. One can recover the usual linear or quadratic optomechanics drift matrices by setting $g_2 = 0$ or $\chi = g_1 = 0$, respectively.
SELECTABLE LINEAR OR QUADRATIC COUPLING IN AN


