Trainable COSFIRE filters for keypoint detection object localization, and pattern recognition

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Contribution

- COSFIRE: Combination of Shifted Filter Responses [1]
- A COSFIRE filter is selective for the geometrical arrangement of edges/lines of a prototype shape of interest
- Trainable: its selectivity is determined from a single prototype in an automatic configuration process
- Tolerant to *rotation*, *scale* and *reflection*

Motivation

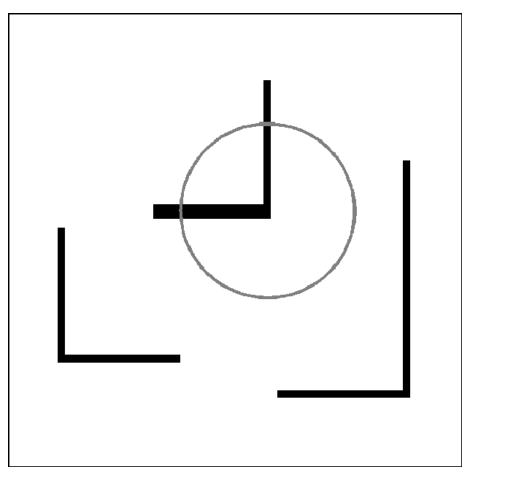
- Some neurons in area V4 of visual cortex are selective to combinations of edges/lines [2]
- Corners and junctions are present in many types of images

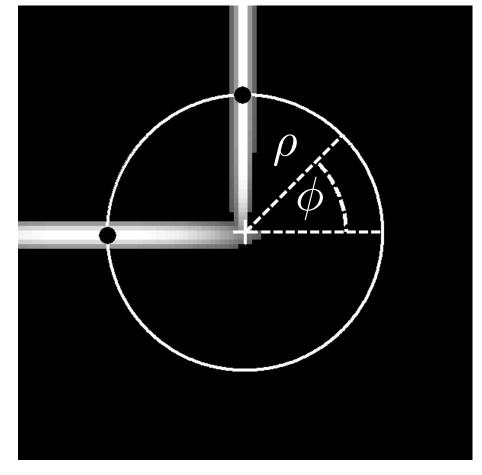




Configuration

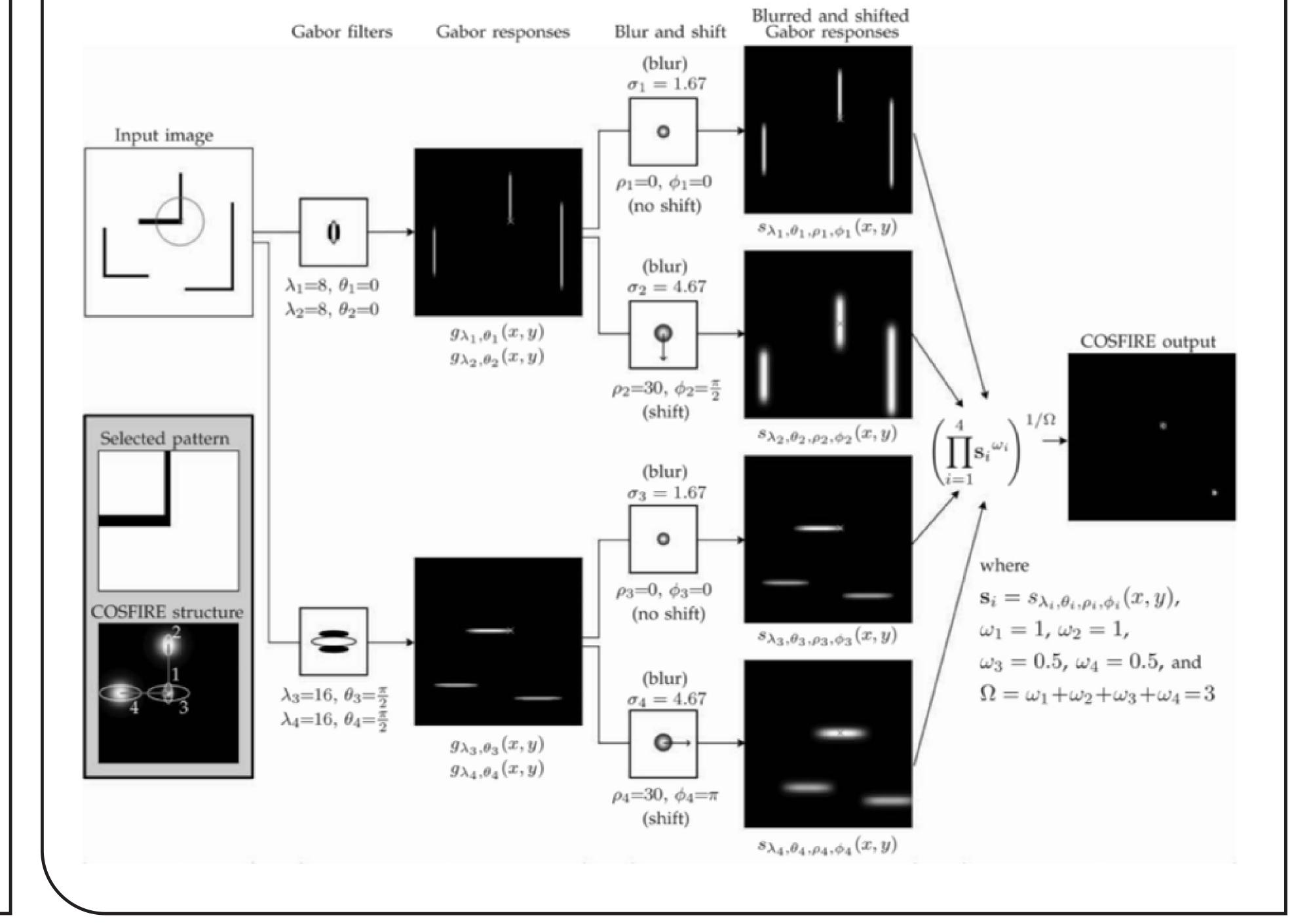
Example of a corner-selective COSFIRE filter





- 1. Let the encircled corner be a prototype pattern
- 2. Apply a bank of Gabor filters to the prototype
- 3. Extract Gabor parameter values (λ_i, θ_i) at local maxima points along some circle(s)
- 4. Extract polar coordinates (ρ_i, ϕ_i) of local maxima points *wrt* to the location indicated by a '+'
- 5. Result is a set $S_f = \{(\lambda_i, \theta_i, \rho_i, \phi_i) \mid i = 1 \dots n_f\}$

Response of a COSFIRE filter



6. For the considered example:

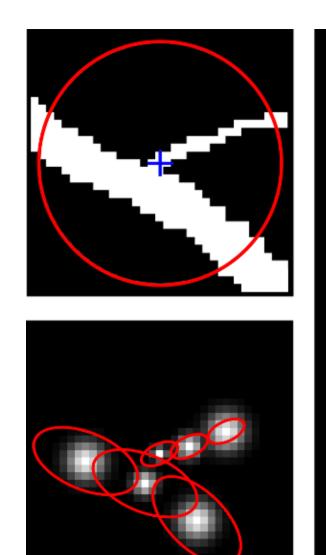
$$S_{f} = \begin{cases} (\lambda_{1} = 8, \ \theta_{1} = 0, \ \rho_{1} = 0, \ \phi_{1} = 0), \\ (\lambda_{2} = 8, \ \theta_{2} = 0, \ \rho_{2} = 30, \ \phi_{2} = \frac{\pi}{2}), \\ (\lambda_{3} = 16, \ \theta_{3} = \frac{\pi}{2}, \ \rho_{3} = 0, \ \phi_{3} = 0), \\ (\lambda_{4} = 16, \ \theta_{4} = \frac{\pi}{2}, \ \rho_{4} = 30, \ \phi_{4} = \pi) \end{cases}$$

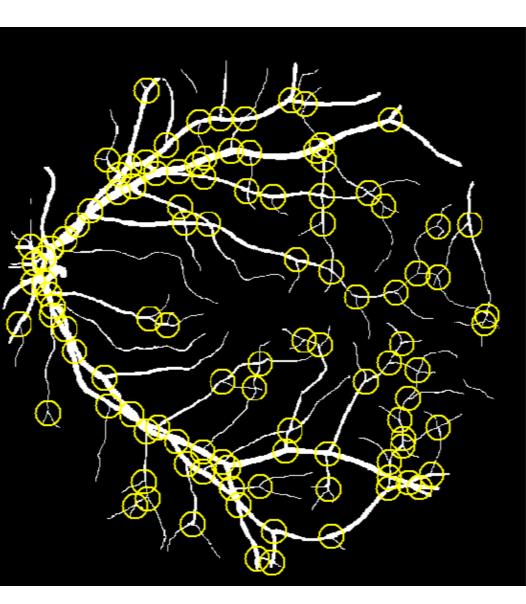
Applications and results

Bifurcation detection in retinal images

Traffic sign detection and recognition

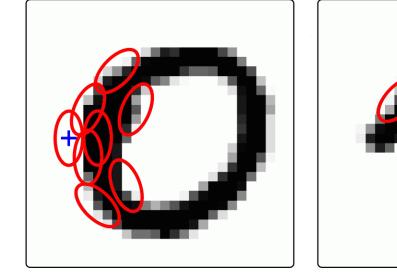
Handwritten digit recognition

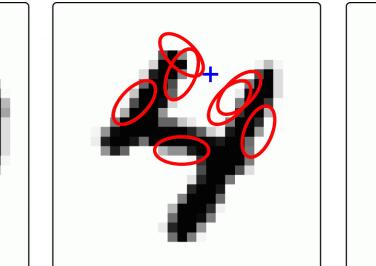


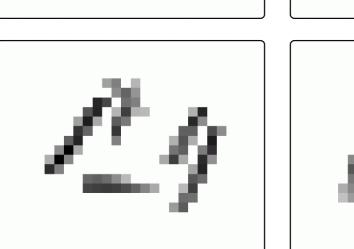














DRIVE data set: 40 retinal images 98.5% recall, 96.09% precision RuG data set: 48 images, 3 kinds of traffic signs 100% recall, 100% precision

MNIST data set: 70,000 images 98.48% recognition rate

Conclusions

- COSFIRE filters are highly effective for keypoint detection, object localization in complex scenes, and pattern recognition
- Versatile: suitable to many computer vision applications
- Conceptually simple and easy to implement
- Matlab code: http://matlabserver.cs.rug.nl/cosfireweb/web/

References

- [1] G Azzopardi and N Petkov. "Trainable COSFIRE Filters for Keypoint Detection and Pattern Recognition". In: *IEEE Transactions on Pattern Analysis and Machine Intelligence* 35.2 (2013), 490–503.
- [2] A Pasupathy and CE Connor. "Responses to contour features in macaque area V4". In: *Journal of Neurophysiology* 82.5 (1999), 2490–2502.